Rigidity of Simplicial Complexes

James Cruickshank, NUI Galway, Bill Jackson^{*}, Queen Mary University of London and Shin-Ichi Tanigawa, University of Tokyo.

A *d*-dimensional framework is a staight line representation of a graph in \mathbb{R}^d . It is rigid if every continuous motion of the vertices which preserves the lengths of the edges results in a framework which is congruent to the original framework. It is globally rigid if every *d*dimensional framework which has the same underlying graph and the same edge lengths is congruent to the original framework. It is known that both properties depend only on the underlying graph when the framework is generic i.e. the set of coordinates of the vertices is algebraically independent over \mathbb{Q} .

After giving a brief introduction to the rigidity of frameworks and the associated *rigidity* matroid, I will survey results on the generic rigidity of the 1-skeletons of simplicial (d-1)complexes in \mathbb{R}^d and then describe a recent result with James Cruickshank and Shin-Ichi
Tanigawa which characterises generic global rigidity for triangulated (d-1)-manifolds in \mathbb{R}^d .
More precisely, we show that, if G is the 1-skeleton of a triangulation of a (d-1)-manifold M, then G is generically globally rigid in \mathbb{R}^d if and only if G is (d+1)-connected and, when d = 2, M is not homeomorphic to the 2-sphere.

Keywords: framework, rigidity, global rigidity, rigidity matroid, simplicial complex, triangulated manifold.